

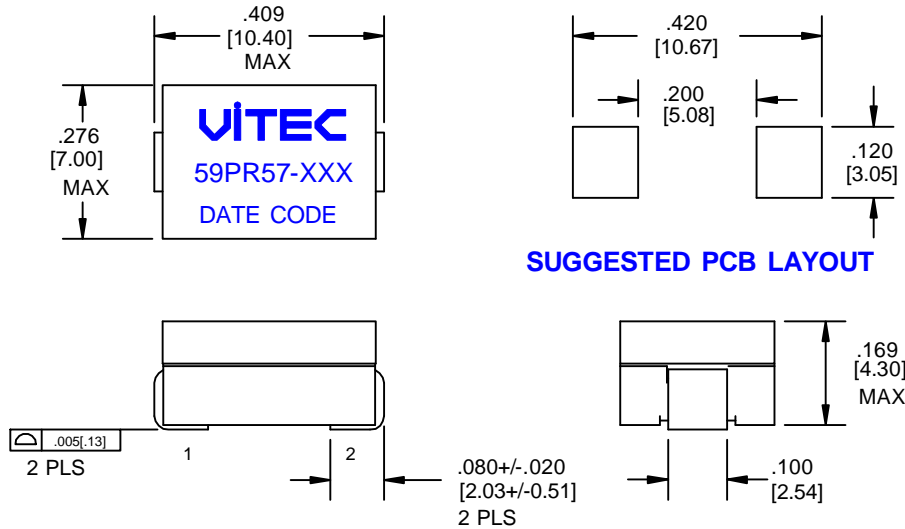
SMD High Frequency Power Inductor

Designed for VRD & VRM 10.X & 11.X Applications

FEATURES

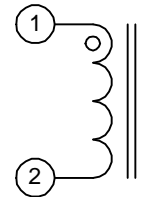
- Low Profile SMT Package
- Operating Frequency of 0.100 - 2.0 MHz
- Extended Operating Temperature Range of -40°C to 125°C
- High Current Handling Capability in the Smallest Footprint

MECHANICAL



ALL DIMENSIONS GIVEN IN INCHES [MM].
TOLERANCES UNLESS OTHERWISE SPECIFIED.
.XX+/-01 [X+/-0.25] .XXX+/-005 [XX+/-0.13] ANGULAR: +/-1°

SCHEMATIC



ELECTRICAL CHARACTERISTICS @ 25°C

Part Number		Inductance @ 0A _{DC} ⁴	Inductance @ I _{rated} ⁴	I _{rated} ¹	DCR	MAX Saturation Current ²			Temp. Rise Current ³	Temp. Rise Factor ⁵
Classic	RoHS	nH	nH	ADC	mOhms	ADC	ADC	ADC	ADC	
		+/-10%	MIN	MAX	+/-10%	-40°C	25°C	125°C	MAX	
59P57-121	59PR57-121	120	86	25	0.45	26	25	20	25	0.036520
59P57-201	59PR57-201	200	144	20	0.45	21	20	16	25	0.060867

Add an "R" to the part number after "P" for the RoHS compliant version

Notes:

- 1.The rated current is the saturation current @ 25°C.
- 2.The I(Saturation) is the current at which the inductance drops by 20% maximum of its value at 0ADC. This current is measured at the stated ambient environment and by applying a short duration pulse current to the component, minimizing the self-heating effects.
- 3.The I(Temp. Rise) is the current at which the temperature of the part increases by a maximum of 50°C. This test is performed with the part mounted on a PCB with traces having 1.7 times the cross sectional area of the copper leads and applying the DC current for a minimum of 30 minutes.
- 4.Inductance is measured at 100 KHz and 1.0 Vrms.
- 5.Temperature Rise can be estimated using the following formulas:

$$\text{Trise (}^\circ\text{C)} = \left(\frac{\text{Core Loss} + \text{DCR Loss}}{2.48} \right)^{0.33}$$

$$\text{DCR Loss (mW)} = \left(\text{IDC}^2 + \left(\frac{\Delta I}{2} \right)^2 \right) \times \text{TYP DCR (mOhms)}$$

$$\text{Core Loss (mW)} = 0.002292 \times (F)^{1.84} \times (\text{Temp. Rise Factor} \times \Delta I)^{2.28}$$

IDC = DC Output Current (ADC)

ΔI = Delta I across the inductor (Amps)

F = Switching Frequency (kHz)

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